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Rev 4 UNIT 0

RKO5 ANNGAL

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1.0 PURPOSE/SCOPE

1.1 Purpose

1.1.1 To clean and verify proper alignment of RKO5 disk drives.

1.2 Scope

1.2.1 To verify that the RKO5 disk drive is operating correctly and that the power supply's are within specifications.

2.0 REFERENCES

2.1 Manuals

- 2.1.1 DEC. RKO5 disk drive Maintenance Manuals.
- 2.1.2 DEC. Print set.

2.2 Flowsheets

2.2.1 NK-21-OP-0-63590-FS1, FS2 Fuel Handling Control System Block Diagram.

3.0 PREREQUISITES

3.1 Preliminary Considerations

- 3.1.1 This procedure will require one man. The time required is about three hours plus two hours for each additional drive.
- 3.1.2 The RKO5 disk drives are located in the F/H control equipment rooms, MATF control room and in the F/H maintenance shop.

3.2 Precautions

- 3.2.1 The pins of the backplane can be easily shorted with catastrophic results. Use an insulated probe tip when measuring voltages.
- 3.2.2 The SERVO motor is powerful. Watch your fingers.
- 3.2.3 The cartridge is not a sealed unit and is extremely vulnerable to dirt, care must be taken to keep the cartridge and the interior of the drive clean.
- 3.2.4 Smoke particles, finger print smudges, or dust specks can cause head crashes.

3.3 Isolation

3.3.1 No required.

3.4 Tools and Equipment

- 3.4.1 Dual Channel Oscilloscope,
- 3.4.2 Fluke multimeter.

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- 3.4.3 Vacuum cleaner,
- 3.4.4 Inspection Mirror,
- 3.4.5 Isopropyl Alcohol,
- 3.4.6 Alignment, Diagnostic & Scratch Cartridges,
- 3.4.7 Screwdrivers, slotted & phillips,
- 3.4.8 Ball Handled Allen Wrenches, 1/16, 5/64, 3/32, 3/16 & 1/8,
- 3.4.9 Head cleaning kit SCN 817C3363
- 3.4.10 Replacement LED's SCN 812B7343, 810A7080.
- 3.5 Quality Assurance
- 3.5.1 Include completed CALL-UP sheet with your Work Report.
- 3.5.2 Note any abnormal conditions, observations or repairs on a Work Report.

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	4.0	PROCE	DURE			
	NOTE:	this prod	cedure is to be done	in conju	nction with the RKO5 QUARTERL	Y PROCEDURE
	4.1	Cleanin	g & Inspection			
	4.1.1	Loosen	the hose clamp and	remove t	the absolute filter.	•
	4.1.2	Clean ai replace	ny dusty areas with ⁻ airduct at this time.	Texpads.	Also inspect airduct for signs of	aging, if necessary
	4.1.3	Install a that the	new filter SCN 8170 velcro strip is in plac	3335. Er e on the	nsure that the filter is snapped int bottom of the filter.	o the blower port and
	4.1.4	Tighten	the hose clamp.			
	4.1.5	Push the	e spindle motor mou off the pulleys. Ensi	inting pla ure that th	te towards the spindle to relieve be ne pulleys are not loose or have r	pelt tension, and slip noved on their shaft.
	4.1.6	With the noticeat	belt removed, checole and excessive, re	k for hori	zontal or vertical wobble of the specific spindle.	pindle; if wobble is
	4.1.7	Using a	Texpad clean the sp	indle and	l drive motor pulleys.	
	4.1.8	Spin disk drive spindle and listen for brush squeaking noise. If brushes are squeaking, loosen the mounting screws and repetition brushes, then retighten screws. Ensure that the curved brushes are centered on the spindle hub and that the brush assembly is not tilted or twisted. Full contact of the brushes to the shaft is necessary to prevent brushes from squealing. If brushes are worn out, install a new brush assembly SCN 817D6044.				ews. Ensure that the sembly is not tilted or it brushes from
	4.1.9	Inspect Otherwis	the spindle drive bel	t. IF it is belt by p	frayed or cracked, install a new bushing the spindle motor mounti	elt. SCN 817C6793.
	4.1.10	Check L	inear Positioner bea	rings for	wear.	
	4.1.11	Disable	the positioner by dis	connecti	ng P5 connector on power supply	/.
	4.1.12	Place a	clean Texpad betwee	en the he	ads to prevent them from contact	ing each other.
	4.1.13	Using a	texpad clean the line	ear positi	oner guides.	
	4.1.14	Without applying undue pressure, move carriage and coil assembly in and out while observing the four bearings on the linear positioner. Each should turn equally; if a bearing stops while moving the carriage, the carriage assembly is not properly aligned. If a bump is felt the bearing may be worn or have a flat spot on it. With either symptom, replacement of the linear positioner is recommended. Reconnect P5 connector, and heads will retract.				
	4.1.15	Remove blower a	the mounting screw ssembly out of RKO	s from th 5, being	e blower shroud using an Allen h careful not to damage the foam s	ead driver and lift the eal.
	4.1.16	If necess	sary, remove the blo	wer moto	r wires from TB-4.	
		Green w Blue wire Black wi	= TB-4, pin 2.			

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4.1.17	Inspec remove	t impeller. If dirty, loo and clean impeller b	sen locki olades.	ng screw holding the impeller to	the motor shaft,
4.1.18	Wire th	ne inside of the blowe	r housina	clean.	
4.1.19	Reinsta	all the impeller and en	ıd plate.	Ensure that the screws are tight a not make contact with the moto	and that the impeller
4.1.20	Reinsta			econnect the wires to TB-4, if the	-
4.2	RKO5	Servo System Adjus	tments		• •
4.2.1	and ins	stall SCRATCH cartrid	ge in driv	to computer, then remove the diversity of the diversity o	time for the
4.2.2	Connect proced	ct scope channel #1 lure below.	probe to	various points on RKO5 backpla	ne noted in the
4.2.3	2.3 Connect scope external trigger input to the RKO5 back plane B05J2.				
4.2.4	Set the	Oscilloscope control	s as follo	ws:	
	Ver Mo	tical de	= CI	า #1	
	• Ser	nsitivity	= 2.	0 V/div. (X10 probe)	
	• Cou	upling	= dc	,	e ÷
,	• Trig	ger	= A		
	• Swe	eep time	= 10	ms/div.	
. •	• Trig	ger mode	= nc	ormal	
	• Cou	upling	= ac		
	• Sou	ırce	= ex	ternal	
	• Slop	pe	= (-)	
4.2.5	Sine An	nplitude (SA) and Offs	set (SO)	Figure 4.1 & 4.2.	
	1. Perl	form a four cylinder o	scillating	seek. <u>X</u> 402	
	Figu	serve A05M1 (SINE Pour Fig. 1. The waveform The metrical about groun	n amplitu	for a scope display similar to the de must be 10 Vdc \pm 1 volt peak	at shown in k to peak and
	3. If ne	ecessary, adjust SA (s the ground summetry.	ee Table	#1, Attachment 6.1) for the corre	ect amplitude and SO
4.2.6	Velocity	Offset (VO)		Figure 4.1 & 4.2	•
	1. Obs	and Figure 4.1 & 4.2.	minimum A small a	s at A05M1 (SINE POSITION) ar amount of ripple at the minimum	e summetrical about voltage levels is

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2. If necessary adjust VO (see Table #1) for the required symmetry.

SIGNAL RETURNS TO GROUND LEVEL

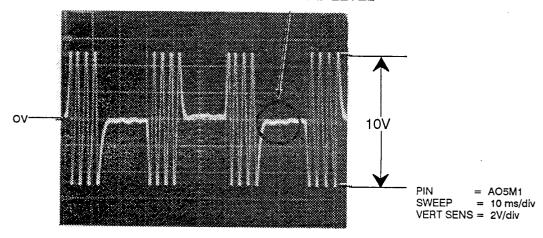


FIGURE 4.1
Sine Amplitude/Offset and Velocity Offset Waveform

SIGNAL RETURNS TO GROUND LEVEL

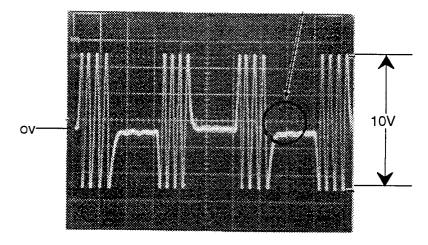


FIGURE 4.2

Incorrect Waveform (Signal not symmetrical about ground)

4.2.7 Cosine Amplitude (CA) and Offset (CO) Figure 4.3.

1. Perform a four cylinder oscillating seek.

<u>X</u>402

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- 2. Observe A05S1 (COS POSITION) for a scope display similar to that shown in Figure 4.3. The waveform amplitude must be 10 Vdc \pm 1 volt peak to peak and symmetrical about ground.
- 3. If necessary, adjust CA (see Table #1) for the correct amplitude and CO for the ground symmetry.

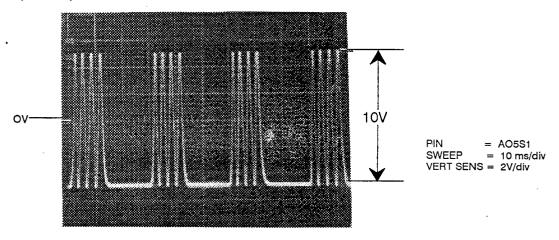
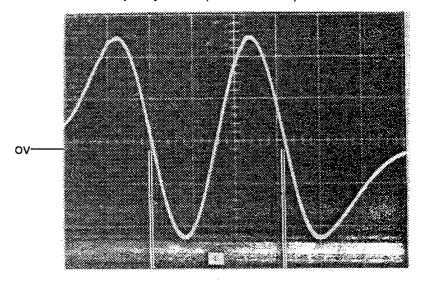


FIGURE 4.3

4.2.8 Velocity Amplitude (VA).

Figure 4.4.

- 1. Perform a two cylinder oscillating seek.
- <u>X</u>401
- 2. Set the scope sweep time to 1 ms/div.
- 3. Observe A05M1 for a scope display similar to that shown in Figure 4.4. The duration of the center cycle must equal 3.2 ms \pm 0.05 ms.
- 4. If necessary, adjust VA (see Table #1) for the correct time.



t = 3.2 ms for RKO5/RKO5J t = 2.3 ms for RKO5F

PIN = AO5M1 SWEEP = 1 ms/div VERT SENS = 2V/div

FIGURE 4.4

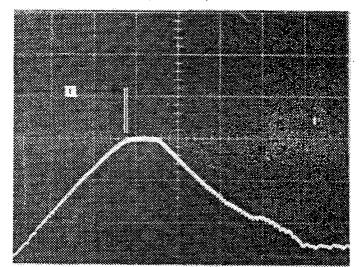
4.2.9 Acceleration (Positioner Current)

Figure 4.5.

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- 1. Perform a 64 cylinder oscillating seek. X404
- 2. Set the scope sweep time to 5 ms/div. and the vertical sensitivity to 0.5 V/div.
- 3. Observe A05H1 (VELOCITY) for a velocity profile as shown in Figure 4.5.
- 4. If necessary, adjust R15 (on H604) for a rise time of 14 ms \pm 1 ms.



t = 14 ms for RKO5/RKO5Jt = 13 ms for RKO5F

PIN = AO5H1 SWEEP = 5 ms/div VERT SENS = 0.5V/div

FIGURE 4.5

4.2.10 Full Stroke Profile

Figure 4.6. X406

- Perform a 202 cylinder oscillating seek.
- 2. Set the scope sweep time to 10 ms/div. and the vertical sensitivity to 0.5 V/div.
- 3. Observe A05H1 (VELOCITY) for a scope display as shown in Figure 4.6. The 0 volt level of the profile must be reached in less than 90 ms from the start of the seek. This figure may not be attainable: In addition, there must be a definite plateau (constant voltage level) at the end of the seek. If this is not the case, recheck the VA and the Acceleration (Positioner Current). Adjust the appropriate potentionmeter (see Table #1) as required to obtain the correct waveform.

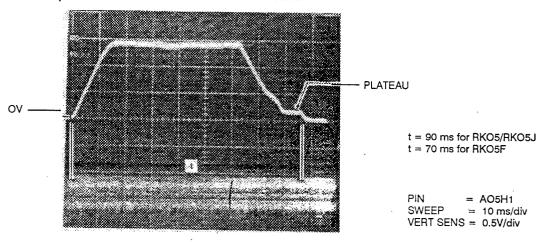


FIGURE 4.6

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4.2.11 Full Stroke Position Waveform

Figure 4.7.

- 1. Maintain the same configuration as for the Full Stroke Profile.
- Set the scope vertical sensitivity to 2 V/div. and observe A05M1 (SINE POSITION) for a scope display similar to that shown in Figure 4.7. The waveform amplitudes at the start and end of the seek must be equal within 5% and the overshoot at the end of the seek must not exceed 1 volt. If overshoot is excessive, recheck the VA and the Acceleration (Positioner Current).

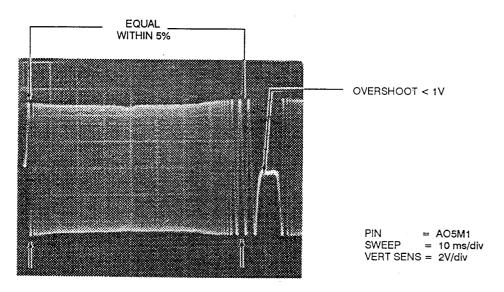


FIGURE 4.7

- 4.2.12 Out Limit (Dynamic Test)
 - 1. At communication printer type CTRL "D".
 - Perform a repetitive restore operation by installing the following jumpers. B08H1 to B08M1 A08M1 to A08T1
 - 3. Trigger the scope from B05K2.
 - 4. Set the scope vertical sensitivity to 1 V/div and observe A05J1 (LIMIT) for a scope display as shown in Figure 4.8. The waveform peak amplitude must be 3 to 3.5 volts with a minimum level of 0.0 volts. In addition, the plateau immediately following the trailing edge must not exceed 0.3 volts. <u>IF NOT</u>, remove jumpers and perform <u>Step 4.2.14</u>. STATIC LIMIT Adjustment.
 - 5. Disconnect both jumpers to halt the repetitive restore.
 - 6. Check the INNIER LIMIT signal by dissabling the positioner using the red maintenance switch (S1) on Servo Amp H640. Select switch (S1) to the down position and physically move the positioner to the inner limit. Now select switch (S1) to the up position, enabling the positioner and if the inner limit signal is operative a restore operation will be initiated and heads will retract.
- 4.2.13 After completion of Step 4.2.12.6 go to the QUARTER PROCEDURE CMP-63591-016. Section 4.4 and complete all remaining steps.

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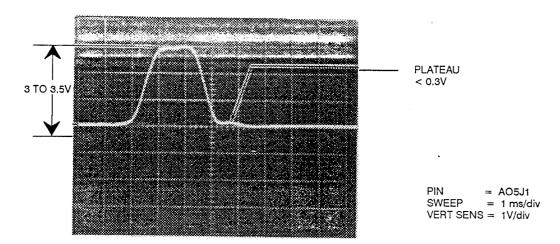


FIGURE 4.8

- 4.2.14 Static Limit Adjustment. Limit Signal Amplitude (LSA) and Offset (LSO)
 - 1. Observe A05J1 with the positioner stationary at center of travel. Adjust LSO for a ground signal at the center of the scope screen.
 - 2. Move the positioner to the inner limit and observe the voltage change on the scope. Similarly, move the positioner to the outer limit and observe the voltage change.
 - 3. Adjust LSA until the smaller voltage level obtained in step above is 3.0 volts.
 - 4. Return the positioner to the center of its travel and readjust LSO for 0.0 volts.
 - 5. Repeat the above steps if necessary.
 - 6. Go back to Step 4.2.12.6

5.0 POSTREQUISITES

- 5.1 Ensure work authorization is surrendered.
- 5.2 File DR for any outstanding problems.
- ___ 5.3 Mark up this procedure noting any errors or omissions. Forward to the Control Maintenance Supervisor if revisions are required.

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6.0 ATTACHMENT

6.1 Table 1 – Servo System Adjustments

Potentiometer*	Function
CA (Cosine Amplitude)	Sets amplitude of COS POSITION signal.
CO (Cosine Offset)	Adjusts COS POSITION symmetry about ground.
SA (Sine Amplitude)	Sets amplitude of SIN POSITION signal.
SO (Sine Offset)	Adjust SIN POSITION symmetry about ground.
LSA (Limit Signal Amplitude)	Simultaneously adjusts amplitude of both Limit signals before digitizing.
LSO (Limit Signal Offset)	Sets zero level of Limit signal with positioner in normal recording area of disk.
VA (Velocity Adjustments)	Calibrates velocity generator.
VO (Velocity Offset)	Adjusts velocity generator output at zero velocity. (Provides) offset control to position loop.)
CURRENT (on H604)	Sets maximum positioner current (determines acceleration).

NOTE: Potentiometers are located on the G938/G938YA PCB (position 5) of the logic assembly; access is obtained by removing the prefilter. They are listed in the table according to their physical orientation; CA is the top most potentiometer as viewed from the rear of the drive with the prefilter removed.

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6.2 RKO5 Alignment Program

ALIGNX

REV 3.1

RKO5 ALIGNMENT PROGRAM

SET UP SWITCH REGISTER AS FOLLOWS: **BINARY VALUE** BITS 0-2 DRIVE # (0-7) BIT 3 0 - ALIGN TO TRACK 1 - OSCILLATING SEEK BETWEEN ZERO AND TRACK BIT 0 - SELECT LOWER HEAD FOR ALIGNMENT 1 - SELECT UPPER HEAD FOR ALIGNMENT BITS 9-11 TRACK TO SEEK / ALIGN TO 0 - CYL 01 -2 4 16 64 5 -. 105 202 ANY CYLINDER YOU DEPOSIT INTO LOC. 37

REFERENCE DIAGNOSTIC SYSTEM HELP FILES FOR ADDITIONAL INFORMATION

CONSOLE CONTROLS

CTRL C - Return to OS8 monitor.

CTRL D - Modify Pseudo-switch register.

CTRL R - Restarts the program.

CTRL U - Erases that line just input.

RETURN - Terminates a line of input.

NOTE: Computer responds with SR=0000.

OCTAL VALUE

Type X401 - X406 for a particular cylinder seek, where X is the drive # being tested.

2	 CYLINDER SEEK 	= X401
4	 CYLINDER SEEK 	= X402
64	- CYLINDER SEEK	= X404
202	– CYLINDER SEEK	= X406
CHE	CK UPPER HEAD	= X205
CHE	CK LOWER HEAD	= X005